

# MULTIPROCESSORS

Mahdi Nazm Bojnordi

Assistant Professor

School of Computing

University of Utah

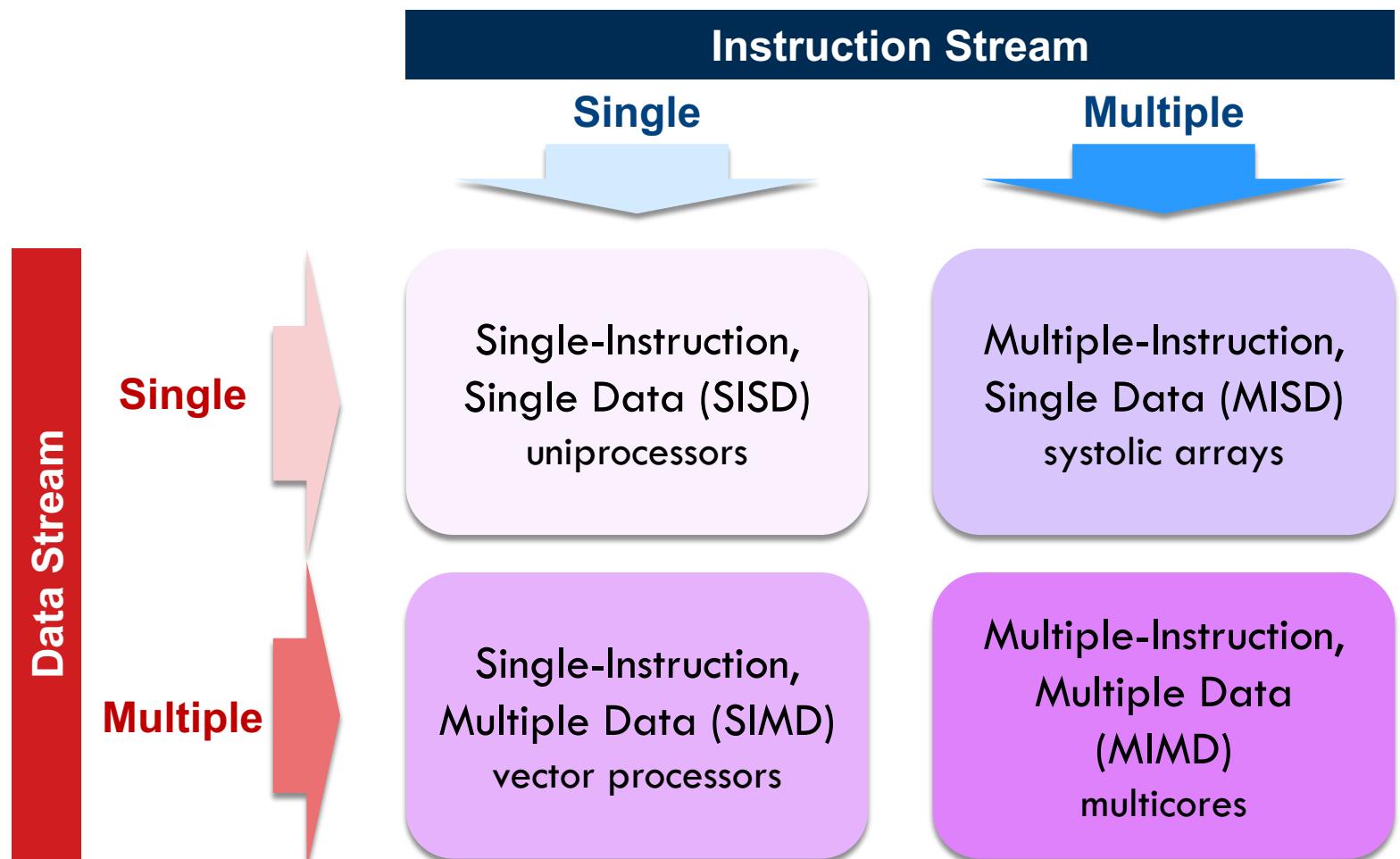
# Overview

---

- This lecture
  - Flynn's taxonomy
  - Vector processing
  - Performance of parallel processing
  - Communication in multiprocessors

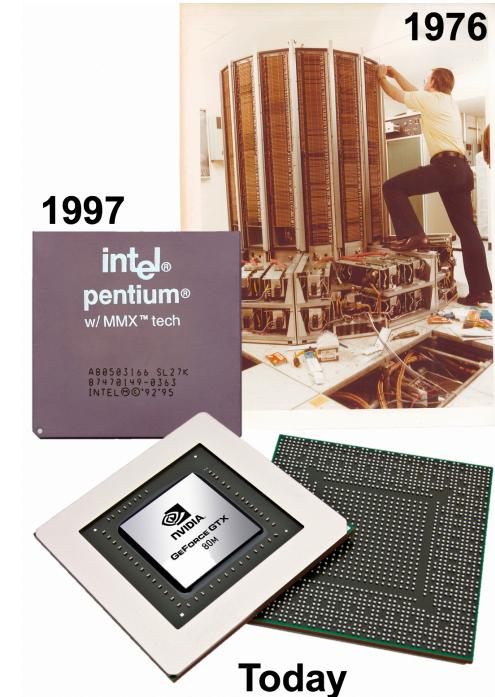
# Flynn's Taxonomy

## □ Data vs. instruction streams



# Data Level Parallelism

- Due to executing the same code on a large number of objects
  - ▣ Common in scientific computing
- DLP architectures
  - ▣ Vector processors—e.g., Cray machines
  - ▣ SIMD extensions—e.g., Intel MMX
  - ▣ Graphics processing unit—e.g., NVIDIA
- Improve throughput rather than latency
  - ▣ Not good for non-parallel workloads



# Vector Processing

## □ Scalar vs. vector processor

```
for(i=0; i<1000; ++i) {  
    B[i] = A[i] + x;  
}
```

**A :**



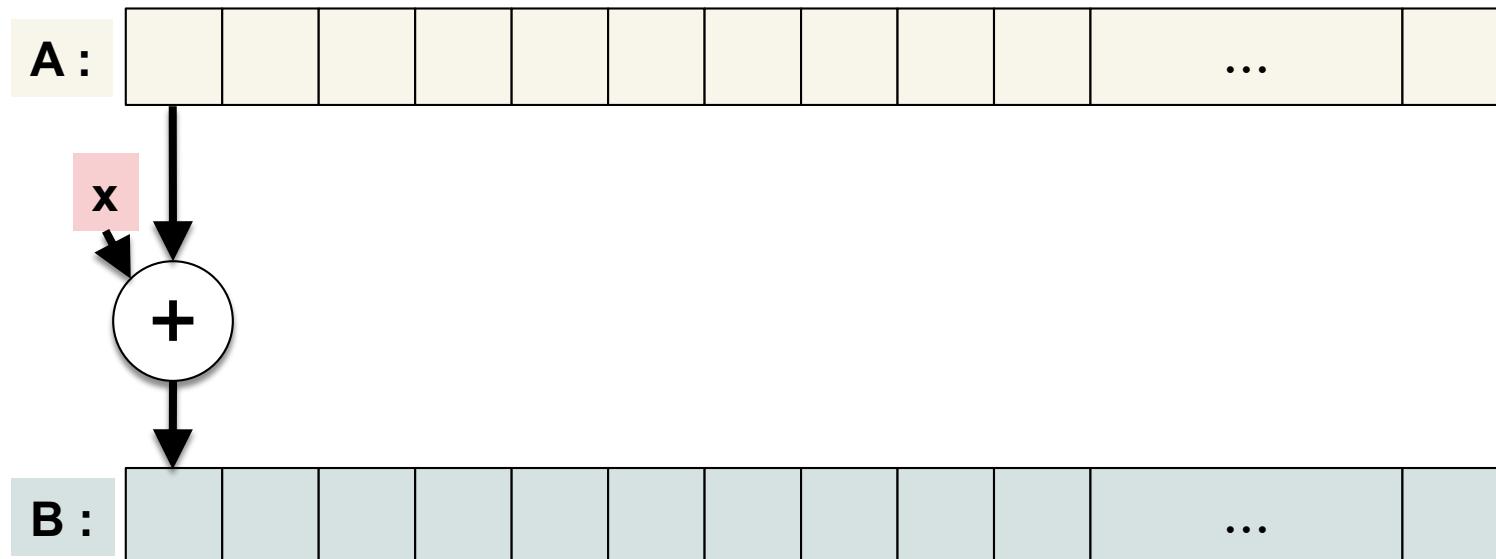
**B :**



# Vector Processing

## □ Scalar vs. vector processor

```
for(i=0; i<1000; ++i) {  
    add r3, r2, r1 ← B[i] = A[i] + x;  
}
```

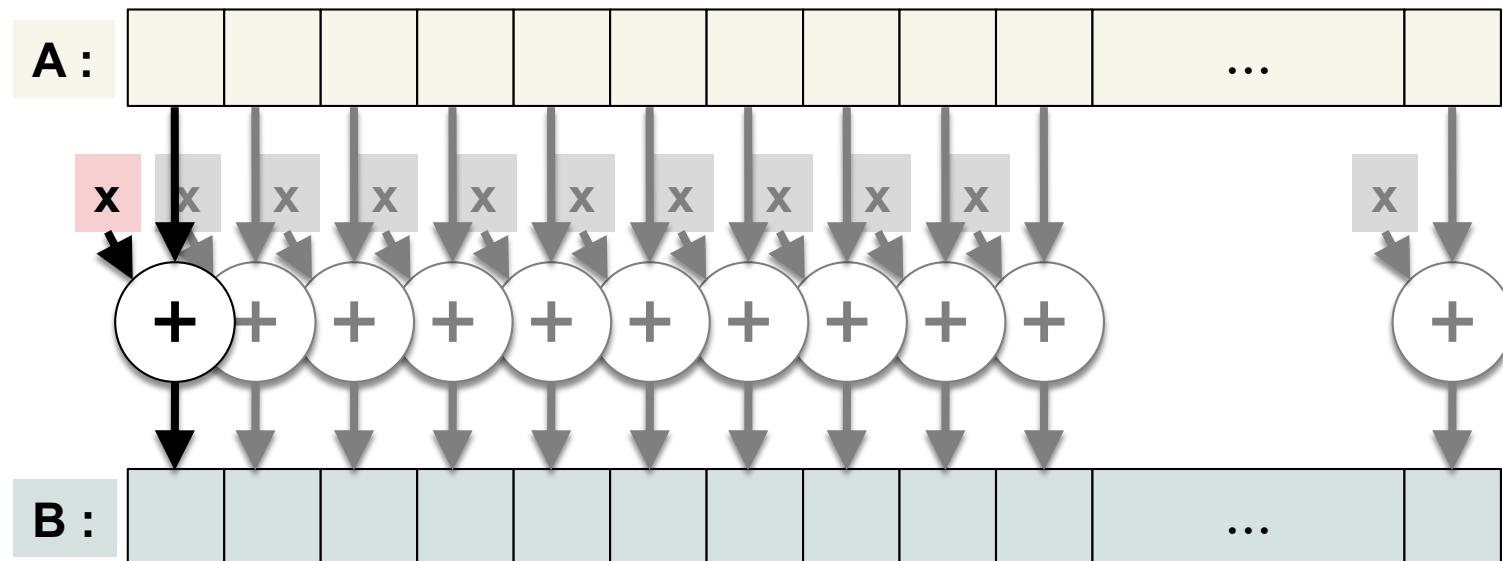


# Vector Processing

## □ Scalar vs. vector processor

```
for(i=0; i<1000; ++i) {  
    B[i] = A[i] + x;  
}
```

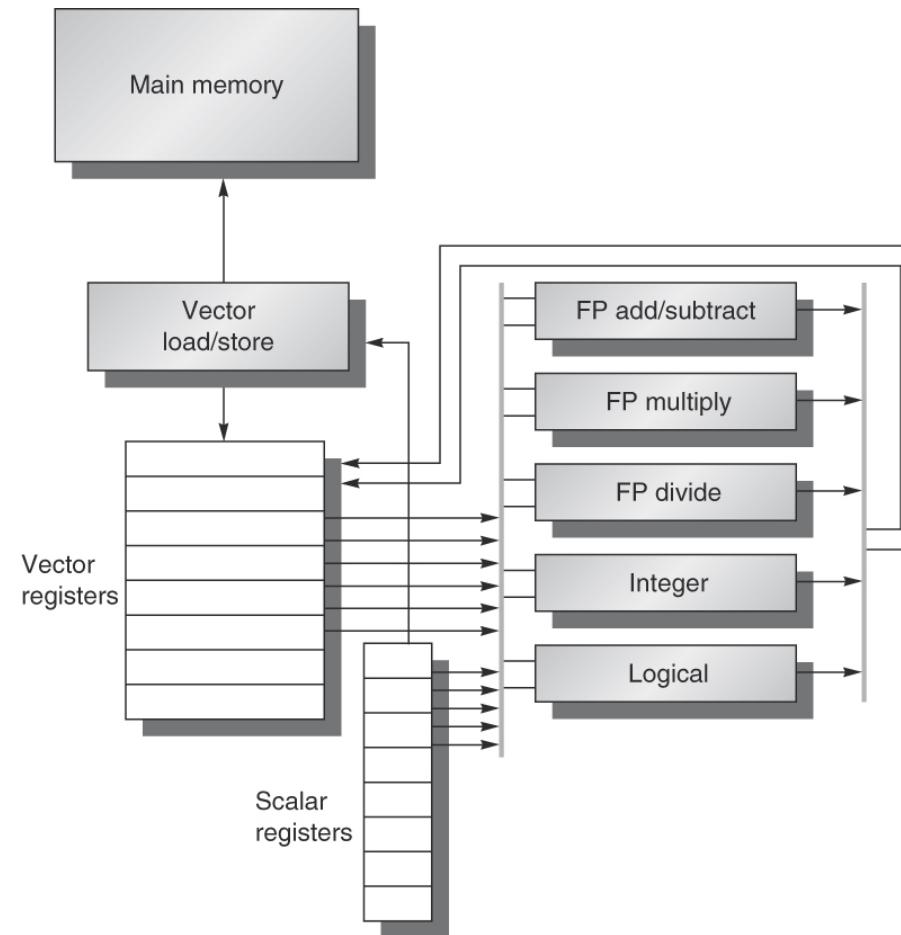
vadd v3, v2, v1



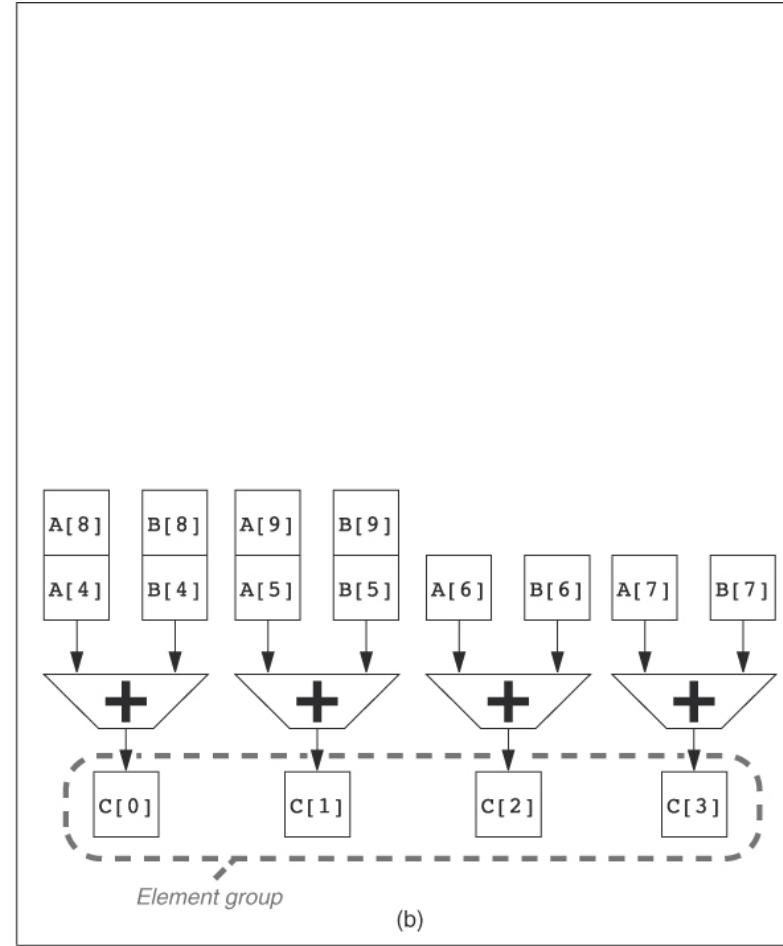
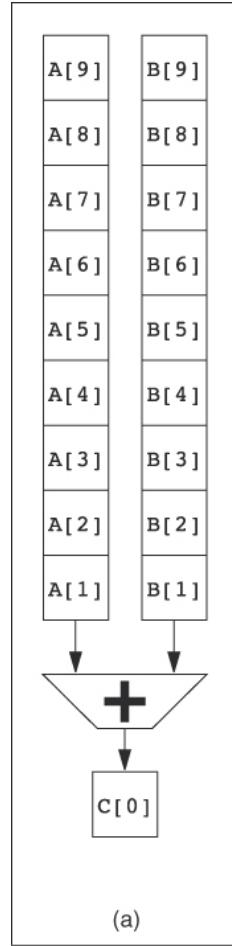
# Vector Processor

- A scalar processor—e.g., MIPS
  - ▣ Scalar register file
  - ▣ Scalar functional units
- Vector register file
  - ▣ 2D register array
  - ▣ Each register is an array of registers
  - ▣ The number of elements per register determines the max vector length
- Vector functional units
  - ▣ Single opcode activates multiple units
  - ▣ Integer, floating point, load and stores

# Basic Vector Processor Architecture



# Parallel vs. Pipeline Units



# Example Code I

- A sequential application runs as a single thread

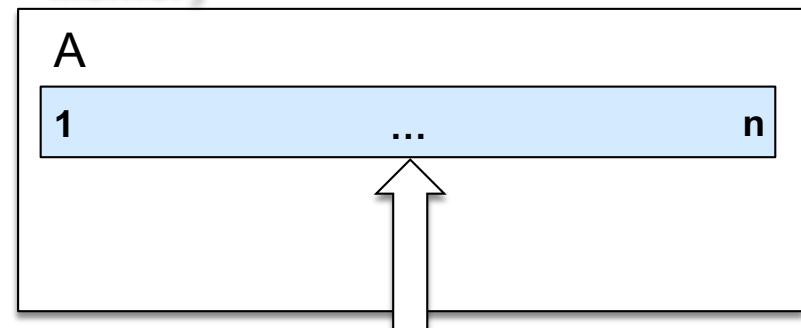
## Kernel Function:

```
void kern (int start, int end) {  
    int i;  
    for(i=start; i<=end; ++i) {  
        A[i] = A[i] * A[i] + 5;  
    }  
}
```

## Single Thread

```
main() {  
    ...  
    kern (1, n);  
    ...  
}
```

## Memory



## Processor

# Example Code I

- Two threads operating on separate partitions

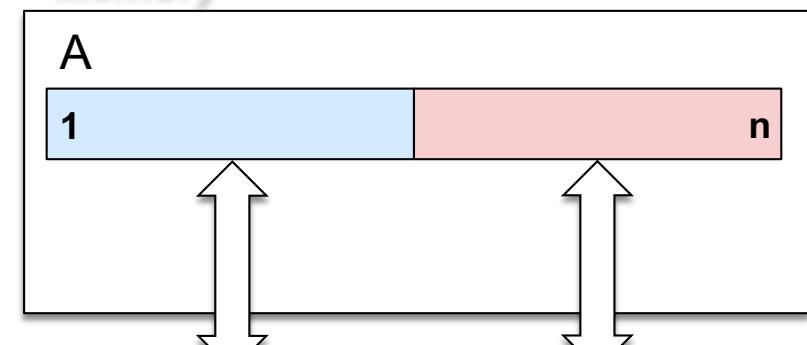
## Kernel Function:

```
void kern (int start, int end) {  
    int i;  
    for(i=start; i<=end; ++i) {  
        A[i] = A[i] * A[i] + 5;  
    }  
}
```

## Thread 0

```
main() {  
    ...  
    kern (1, n/2);  
    ...  
}
```

## Memory



## Processor

## Thread 1

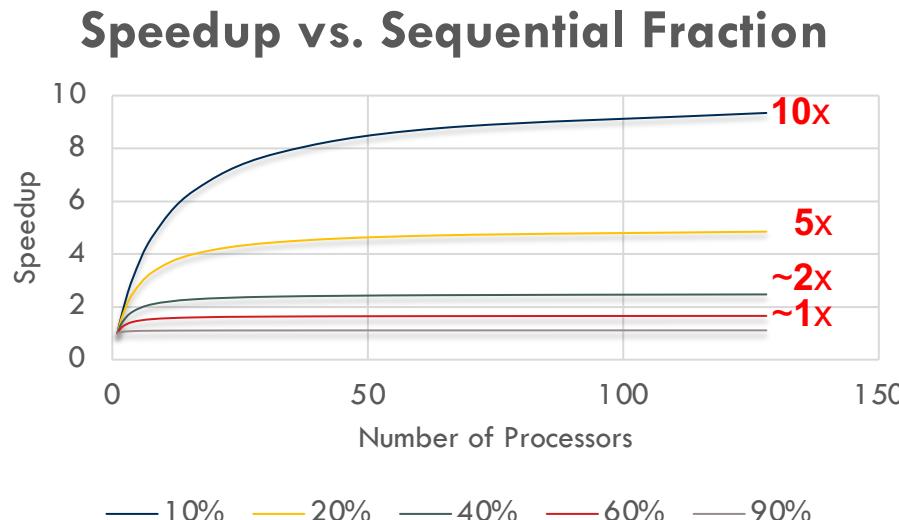
```
kern (n/2+1, n);
```

# Performance of Parallel Processing

- Recall: Amdahl's law for theoretical speedup
  - ▣ Overall speedup is limited to the fraction of the program that can be executed in parallel

$$speedup = \frac{1}{f + \frac{1-f}{n}}$$

f: sequential fraction



# Example Code II

- A single location is updated every time

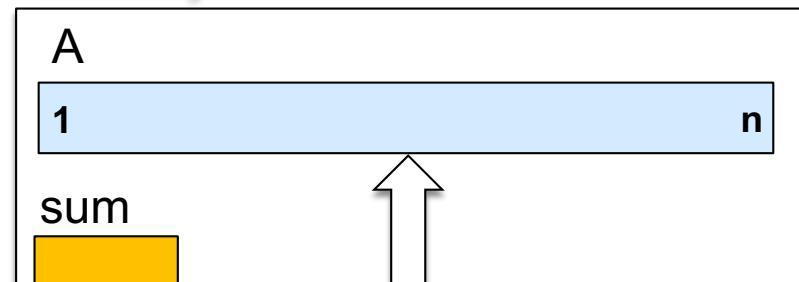
## Kernel Function:

```
void kern (int start, int end) {  
    int i;  
    for(i=start; i<=end; ++i) {  
        sum = sum * A[i];  
    }  
}
```

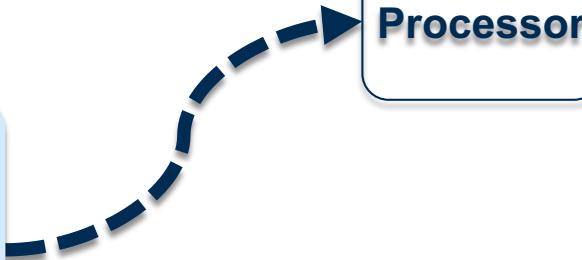
## Thread 0

```
main() {  
    ...  
    kern (1, n);  
    ...  
}
```

## Memory



## Processor



# Example Code II

- Two threads operating on separate partitions

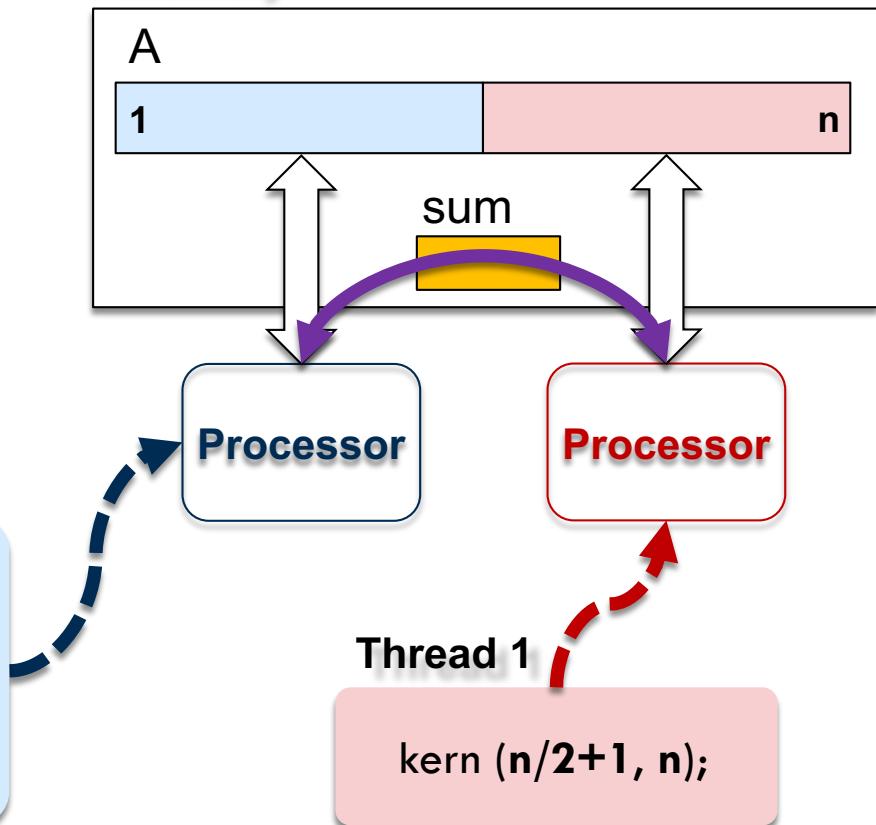
## Kernel Function:

```
void kern (int start, int end) {  
    int i;  
    for(i=start; i<=end; ++i) {  
        sum = sum * A[i];  
    }  
}
```

## Thread 0

```
main() {  
    ...  
    kern (1, n/2);  
    ...  
}
```

## Memory



## Thread 1

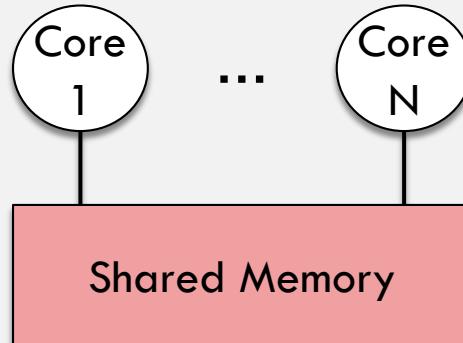
```
kern (n/2+1, n);
```

# Communication in Multiprocessors

## □ How multiple processor cores communicate?

### Shared Memory

- Multiple threads employ shared memory
- Easy for programmers (loads and stores)



### Message Passing

- Explicit communication through interconnection network
- Simple hardware

